

Department of Mechanical Engineering

ME 8692 – Finite Element Analysis

Unit I – Introduction - MCQ Bank

What is a matrix?
 a) Group of elements
 b) Array of elements
 c) Group of columns and rows
 d) Array of numbers
 Answer: b

2. Which of the following is a row vector? a) [0 1 2] F01 b) 1 c) $\begin{bmatrix} 0 & 1 \\ 1 & 2 \end{bmatrix}$ d) None of the above Answer: a 3. $(A B C)^{T} =$ a) (C B A)^T b) $B^T C^T A^T$ c) $\mathbf{C}^{\mathrm{T}} \mathbf{B}^{\mathrm{T}} \mathbf{A}^{\mathrm{T}}$ \dot{d} $A^T B^T C^T$ Answer: c 4. The derivative of Ax with respect to variable x_p is given by _____ a) $d/dx(A x) = x_p$ b) $d/dx(x_p) = A x$ c) $\int A x = x_p$ d) $\int x_p = Ax$ Answer: a 5. A symmetric matrix is called _____, if all its Eigen values are strictly positive i.e., greater than zero. a) Negative definite b) Positive definite c) Co- definite d) Alternative definite

Answer: b

6. A A⁻¹=A⁻¹A is a condition for _____ a) Singular matrix b) Nonsingular matrix c) Matrix inversion d) Ad joint of matrix Answer: c 7. A positive definite symmetric matrix A can be decomposed into form $A=LL^{T}$ this decomposition is called a) Cholesky b) Rayleighs c) Galerkins d) Potential energy Answer: a 8. Det(A- λ I)=0 is a a) Characteristic equation b) Matrix equation c) Inversion of matrix d) Cholesky's equation Answer: a 9. $\begin{bmatrix} 2 & 1 & 3 \\ 0 & 8 & 4 \end{bmatrix}$ is a _____ 0 0 2 a) Principle diagonal matrix b) Upper triangular matrix c) Lower triangular matrix d) Singular matrix Answer: b 10. $A = \begin{bmatrix} 3 & 2 & 1 \\ 4 & 5 & -8 \\ 10 & 0 & 5 \end{bmatrix}$ Then det (A) = a) 120 b) -80 c) -175 d) 0 Answer: c 11. From the following, which type of element is not two dimensional? (A) Rectangle (B) Quadrilateral (C) Parallelogram **(D)** Tetrahedron

Answer D

12. From the following, which type of element is not three dimensional?

(A) Hexahedron

(B) Quadrilateral

(C) Rectangular prism

(D) Tetrahedron

Answer B

13. For truss analysis, which type of elements are used?

(A) Triangle

(B) Bar

(C) Rectangle

(D) Parallelogram

Answer B

14. To solve the FEM problem, it subdivides a large problem into smaller, simpler parts that are called

(A) finite elements(B) infinite elements(C) dynamic elements(D) static elementsAnswer A

15. The art of subdividing the structure into a convenient number of smaller elements is known as

(A) assemblage
(B) continuum
(C) traction
(D) discretization
Answer D

16. The sum of the shape function is equal to
(A) 0
(B) 0.5
(C) 1
(D) 2
Answer C

17. A triangular plane stress element has how many degrees of freedom?

(A) 3 (B) 4 (C) 5 (D) 6 Answer D

18. Number of displacement polynomials used for an element depends on ______.

(A) nature of element(B) type of an element(C) degrees of freedom(D) nodesAnswer C

19. On gathering stiffness and loads, the system of equations is given by
(A) KQ=F
(B) KQ≠F
(C) K=QF

(D) $K \neq QF$

Answer A

20. The finite element method is mostly used in the field of

(A) structural mechanics

(B) classical mechanics

(C) applied mechanics

(D) engineering mechanics

Answer D

21. At fixed support, the displacements are equal to

(A) 1

(B) 2

(C) 3

(D) 0

Answer D

22. In FEA, the sub domains are called as ______.

(A) Particles

(B) Molecules

(C) Elements

(D) None

Answer C

23. The numbers of node for 1 D element are

(A) 1

(B) 2

(C) 3 (D) 0

Answer B

24. Finite element analysis deals with _____.

(A) Approximate numerical solution

(B) Non-boundary value problems

(C) Partial differential equations

(D) Laplace equations

Answer A

- 25. Stiffness matrix depends on
- (A) Material
- (B) Geometry
- (C) Both material and geometry(D) None of the above

Answer C